



worm drives



production programme

BASIC INFORMATION

- * PSL, a. s., is a bearing and slewing ring manufacturer with many years of tradition and experience.
- * PSL, a. s., has a developed, utilized and certified system of the quality assurance programme according to the standard DIN EN ISO 9001.
- * This publication contains basic information on PSL worm drives and their mounting and maintenance.
- * The PSL worm drive system is a compact unit (slewing ring + base plate + worm) suitable for slow rotation with a continuous/cyclical movement capable of handling combined loads.
- * Solutions to complex applications involving PSL worm drives can be provided by the experts of the PSL Technical Department.
- * The contents of this publication have been carefully reviewed, however due to continuous technical development, PSL reserves the right to make technical changes and/or amendments without prior notice.



PSL WORM DRIVES

The universal design of PSL worm drive allows:

- continuous or cyclical rotation of the connected superstructure
- various connections with the driving motor (right or left side per customer's request)
- simple installation
- rational space utilization
- reliable operation with low maintenance requirements

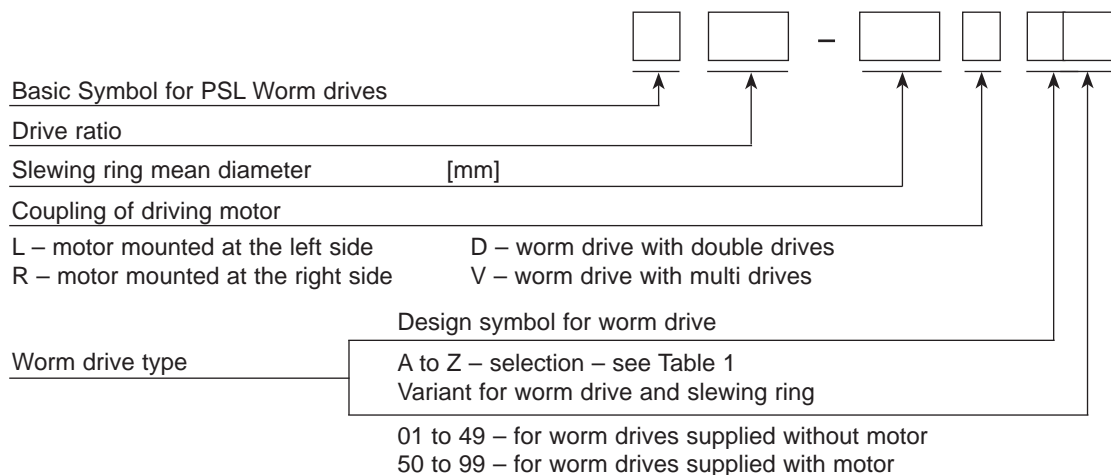
The gear is self-locking, therefore a break is not necessary.

PSL open/covered worm drive systems are produced with multiple combinations suitable for most common applications, such as aerial platforms, positioners and cranes etc.





PART NUMBER DESIGNATION OF PSL WORM DRIVE SYSTEMS



Example of designation:

IP107-422LD01

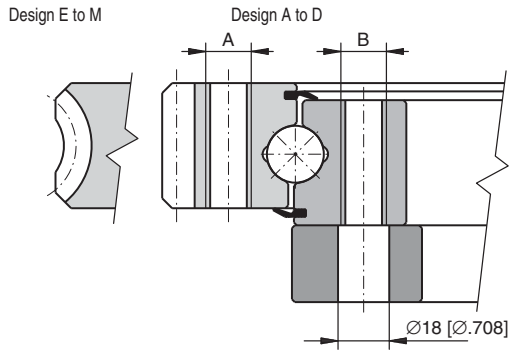
- IP** – PSL worm drive
107 – drive ratio 107
422 – slewing ring mean diameter 422
L – motor at the left side
D01 – worm drive and slewing ring type D01
(helical gear – covered – welded – worm drive supplied without motor)

Table 1

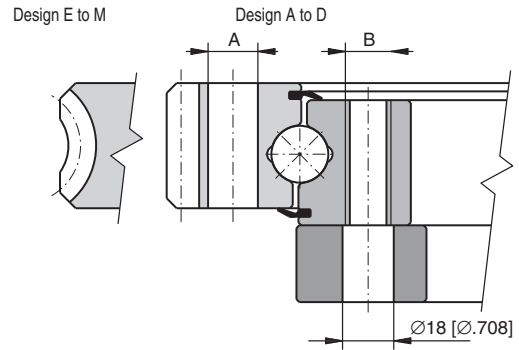
Design Symbol	Type of slewing ring gear					Type of worm drive				
	Helical	Globoidal		Straight	Other	Open	Covered	Casting	Welded	Other
		Steel	Bronze							
A	*					*		*		
B	*					*			*	
C	*						*	*		
D	*						*		*	
E		*				*		*		
F		*				*			*	
G		*					*	*		
H		*					*		*	
J			*			*		*		
K			*			*			*	
L			*				*	*		
M			*				*		*	
N				*		*		*		
O				*		*			*	
P				*			*	*		
R				*			*		*	
S										
T										
U										
V										
W										
X										
Y										
Z										

BASIC TYPES OF WORM DRIVES AND SLEWING RINGS

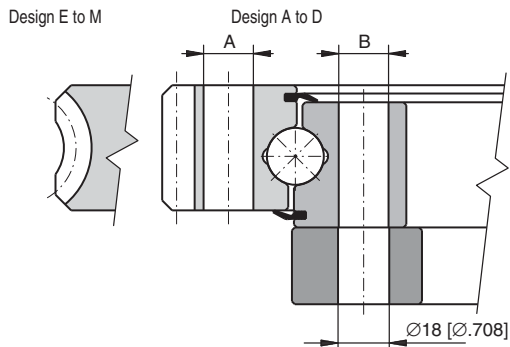
TYPE 01: A;B=M16
TYPE 05: A;B=5/8"-11UNC-2B



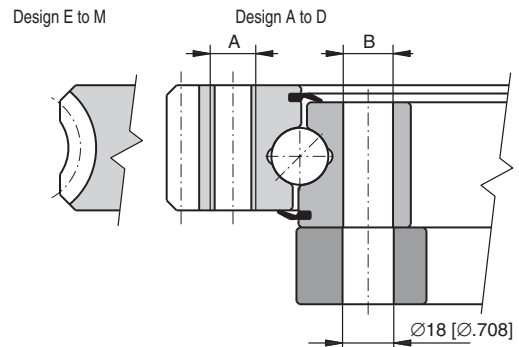
TYPE 02: A=Ø17.5 [Ø.69]; B=M16
TYPE 06: A=Ø17.5 [Ø.69]
B=5/8"-11UNC-2B



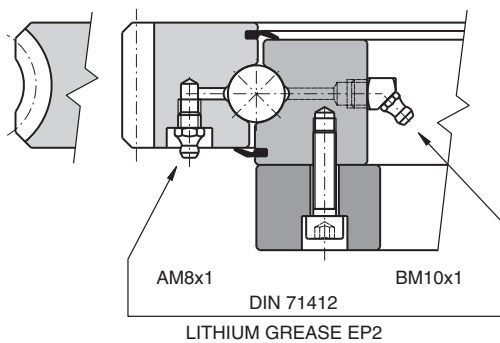
TYPE 03: A;B=Ø17.5 [Ø.69]
TYPE 07: A;B=Ø17.5 [Ø.69]



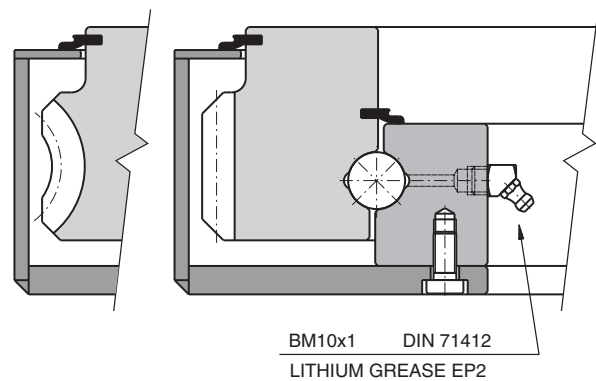
TYPE 04: A=M16; B=Ø17.5 [Ø.69]
TYPE 08: A=5/8"-11UNC-2B
B=Ø17.5 [Ø.69]



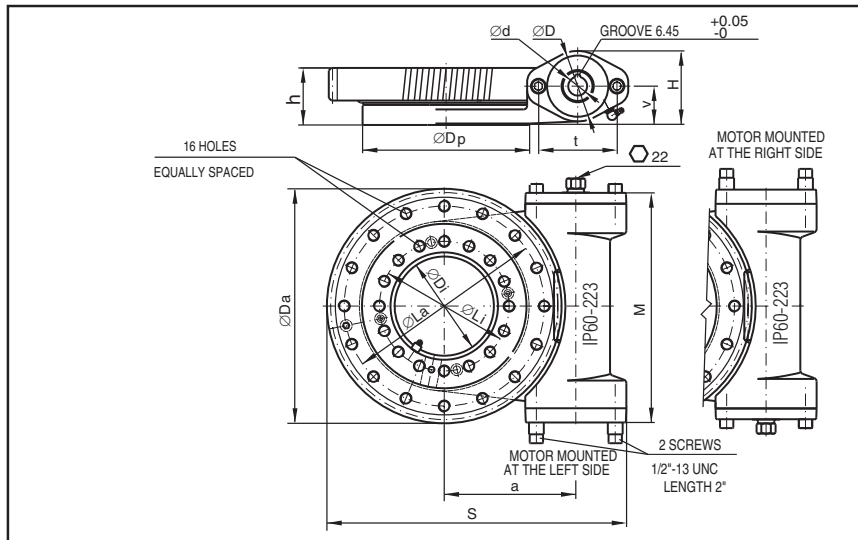
OPEN WORM DRIVES
TYPES 01 TO 08



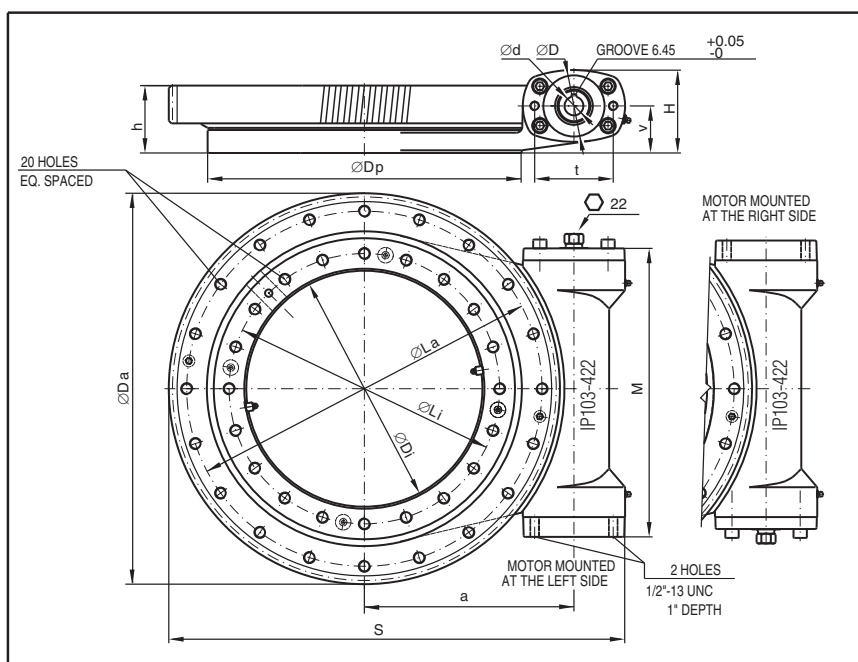
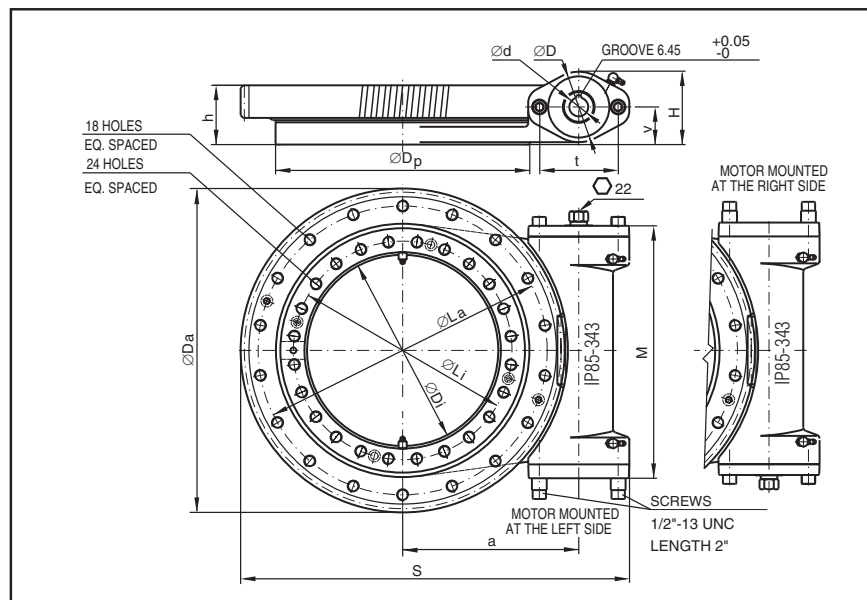
COVERED WORM DRIVES



OPEN WORM DRIVES



Medium worm drive
IP85-343L/R
Design A



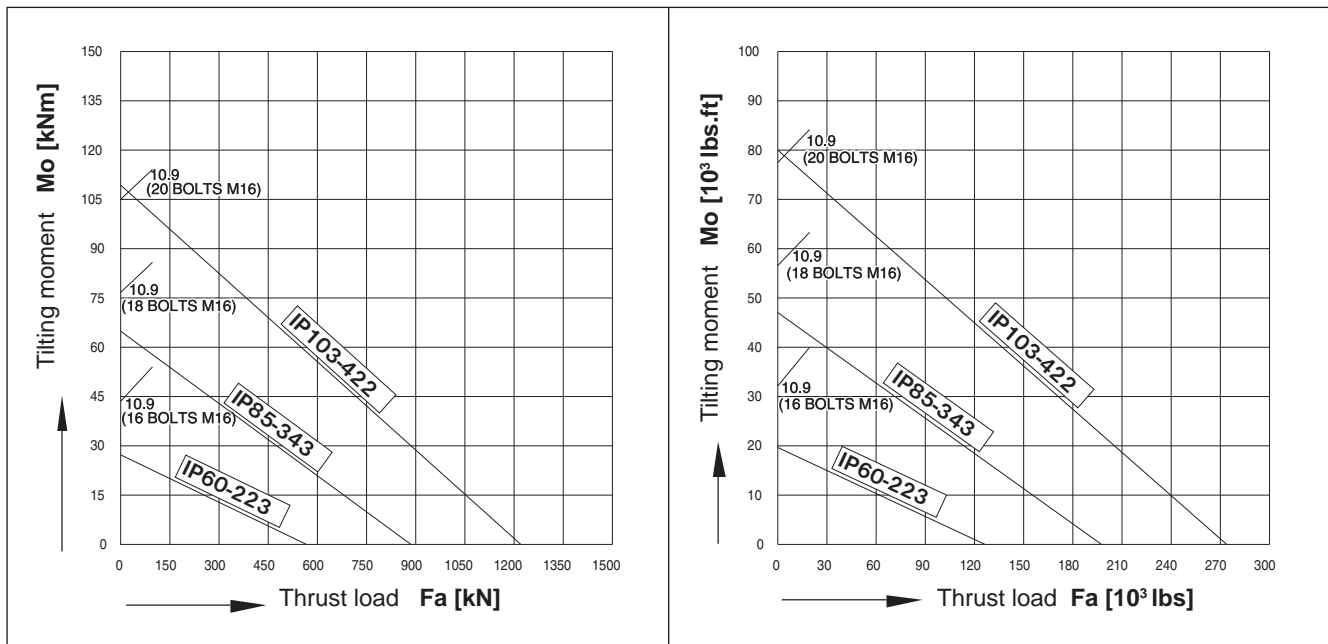
Boundary dimensions for worm drives, design A

Table 2

Designation	IP 60-223		IP 85-343		IP 103-422	
	[mm]	[inch]	[mm]	[inch]	[mm]	[inch]
ϕd	25.5	1.004"	25.5	1.004"	25.5	1.004"
ϕD	82.6	3.25"	82.6	3.25"	82.6	3.25"
ϕLi	175	6.89"	295	11.614"	365	14.37"
ϕLa	270	10.63"	390	15.354"	479.4	18.874"
ϕDi	134	5.276"	258	10.157"	300	11.811"
ϕDa	316.6	12.465"	437.3	17.217"	527.8	20.78"
ϕDp	225	8.86"	343	13.5"	425	16.7"
h	77	3.031"	80	3.15"	91	3.58"
H	98.5	3.88"	98.5	3.88"	111	4.37"
v	52.4	2.063"	50.8	2"	63.5	2.5"
t	106.4	4.189"	106.4	4.189"	106.4	4.189"
a	177.539	6.9897"	237.6	9.3543"	282.8	11.13"
S	405	15.95"	527	20.75"	617.5	24.3"
M	312	12.3"	343	13.5"	389	15.31"

Diagram for limiting static load worm drives, design A

Table 3

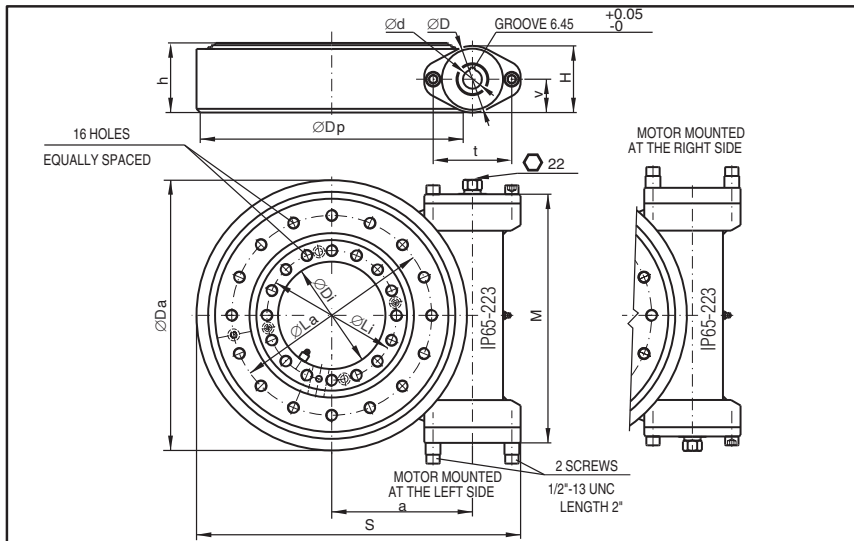


General parameters for worm drives, design A

Table 4

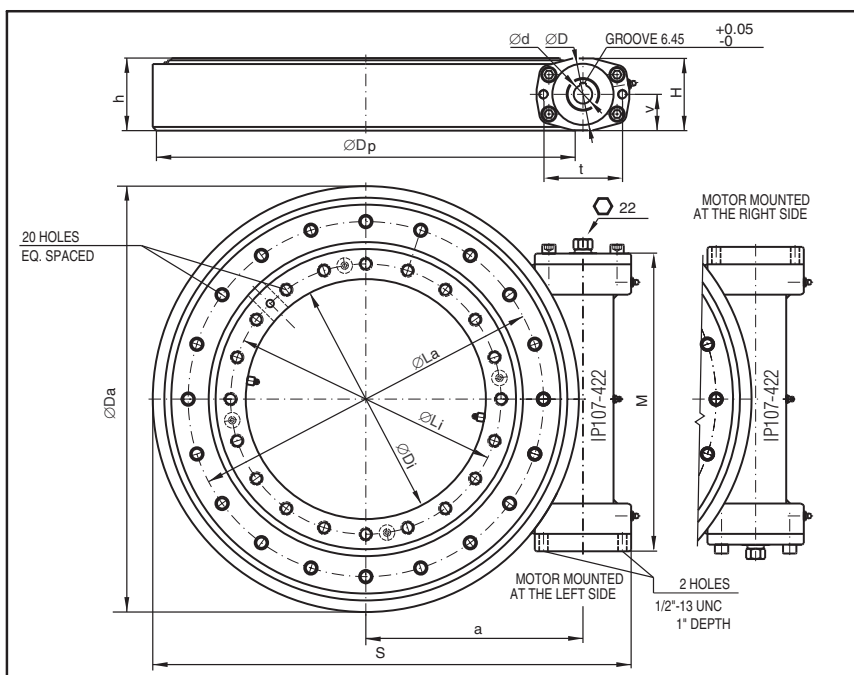
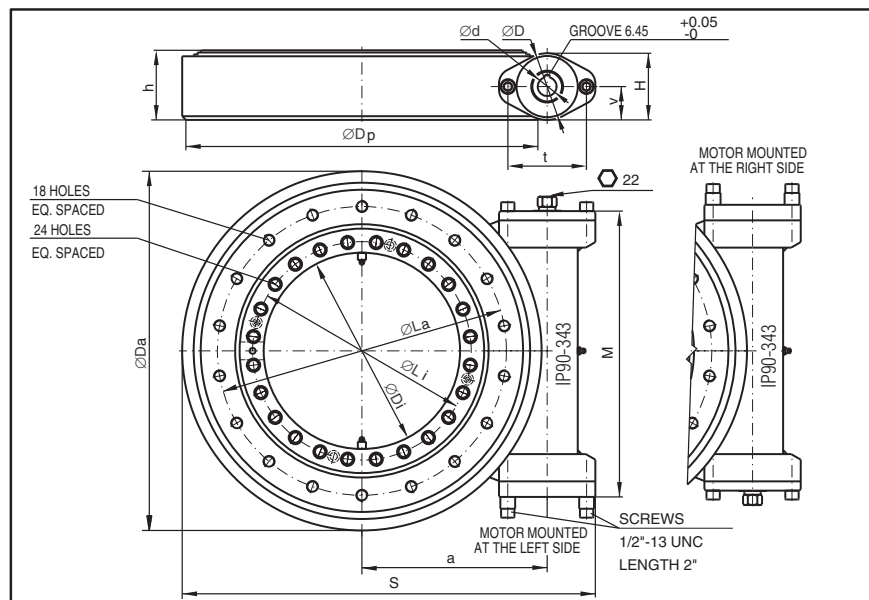
Specification	Unit	IP60-223	IP85-343	IP103-422
Weight	[kg]	37	51	86
	[lb]	82	112	190
Input torque	[Nm]	58	54	108
	[lb.ft]	43	40	80
Output torque	[Nm]	2800	3640	8900
	[lb.ft]	2065	2685	6564
Max. output rotation	[rpm]	13	10	8

COVERED WORM DRIVES



Small worm drive
IP65-223L/R
Design D, H, M

Medium worm drive
IP90-343L/R
Design D, H, M



Heavy duty worm drive
IP107-422L/R
Design D, H, M

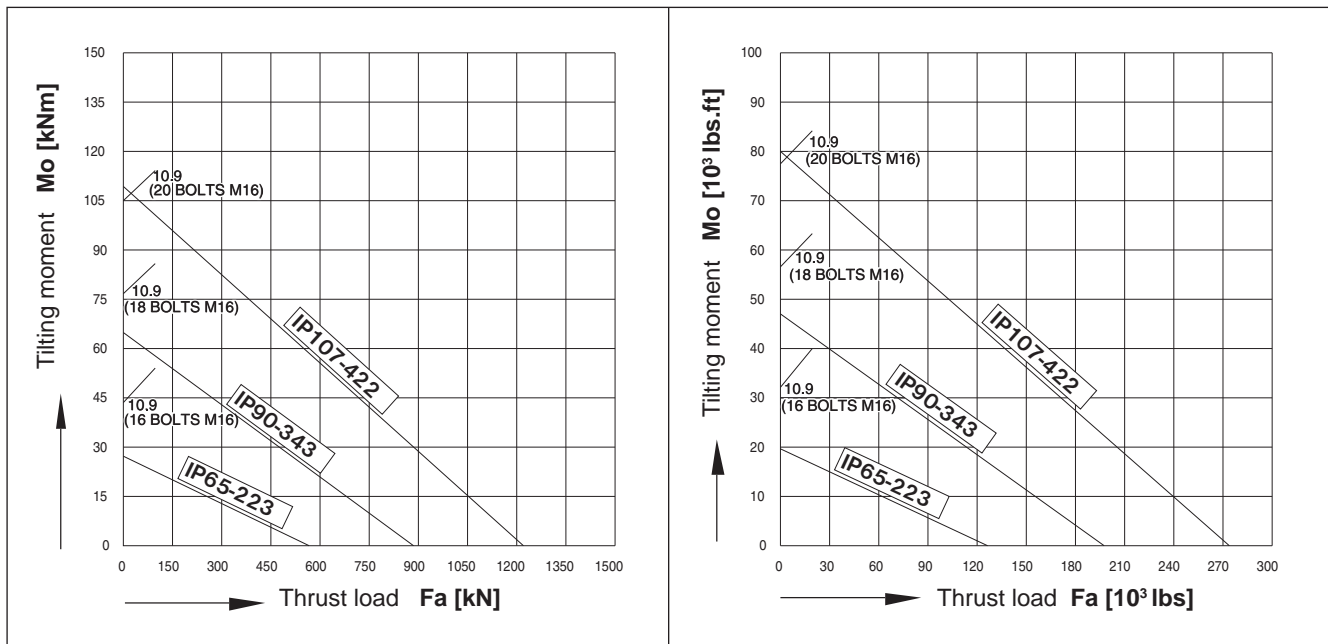
Boundary dimensions for worm drives, design D, H, M

Table 5

Designation	IP65-223		IP90-343		IP107-422	
	[mm]	[inch]	[mm]	[inch]	[mm]	[inch]
ϕd	25.5	1.004"	25.5	1.004"	25.5	1.004"
ϕD	82.6	3.25"	82.6	3.25"	82.6	3.25"
ϕLi	175	6.89"	295	11.614"	365	14.37"
ϕLa	270	10.63"	390	15.354"	479.4	18.874"
ϕDi	145	5.708"	265	10.433"	324	12.754"
ϕDa	365	14.370"	485	19.094"	575	22.64"
ϕDp	355	13.796"	475	18.700"	565	22.25"
h	94	3.70"	94	3.70"	98	3.86"
H	90	3.54"	90	3.54"	97	3.81"
v	45	1.772"	45	1.772"	49	1.93"
t	106.4	4.189"	106.4	4.189"	106.4	4.189"
a	190	7.480"	250	9.842"	293	11.54"
S	438	17.05"	558	21.97"	645.5	24.51"
M	336	13.3"	386	15.2"	402	15.83"

Diagram for limiting static load worm drives, design D, H, M

Table 6



General parameters for worm drives, design D, H, M

Table 7

Specification	Unit	IP65-223	IP90-343	IP107-422
Weight	[kg]	51	74	110
	[lb]	112	163	243
Input torque	[Nm]	92	83	175
	[lb.ft]	68	61	129
Output torque	[Nm]	2980	3740	9350
	[lb.ft]	2198	2758	6896
Max. output rotation	[rpm]	13	10	8

WORM DRIVE SELECTION

In order to decide on which worm drive size is applicable, the following data is needed:

- size, direction and time utilization of the operating load
- required life
- operating rotational speed, or number of work cycles/working angle
(1 work cycle = 2 working angles)
- work environment requirements
- mounting and maintenance requirements

The priority criterion is a reliable load transmission, i. e. adequacy of the raceways, gear and fixing bolts.

Calculation of equivalent axial and moment static load		Table 8
Formula	Conditions of validity	
$F'_{OA} = (F_{OA} + 5,05 \cdot F_{OR}) \cdot s_o$ $M'_{OK} = M_{OK} \cdot s_o$	$0,1 < \frac{F_{OR}}{F_{OA}} < 8$	$e > 2$
$F'_{OA} = (1,23 \cdot F_{OA} + 2,68 \cdot F_{OR}) \cdot s_o$ $M'_{OK} = 1,23 \cdot M_{OK} \cdot s_o$	$0,1 < \frac{F_{OR}}{F_{OA}} < 8$	$e \leq 2$

F_{OA}	– Σ axial static forces on the slewing ring	[kN]
F_{OR}	– Σ radial static forces on the slewing ring	[kN]
M_{OK}	– Σ tilting static moments on the slewing ring	[kNm]
s_o	– static safety factor	[–]
	$s_o = 1$ for normal operating conditions	
	$s_o = 1.1$ to 1.5 – according to operating conditions	
e	$= \frac{2000 \cdot M_{OK}}{F_{OA} \cdot D_s}$ – load eccentricity parameter	[–]
D_s	– mean diameter of slewing ring	[mm]

Note: – if $\frac{F_{OR}}{F_{OA}} < 0,1$ – it is not necessary to take into account the radial force when calculating the equivalent load

How to proceed when selecting a suitable worm drive:

The calculated values of the equivalent axial and moment static loads are defined in their respective coordinates system marked by the operating point in the diagram of a limiting static load (tables 3 and 6). The calculated operating point must lie under the curve for the limiting static loads of raceways and bolts.

FASTENING BOLTS

For fastening of the worm drives, bolts class 10.9 (according to ISO) or grade 8 (according to SAE) must be used.

The fastening bolt length has to be $l = 5 \times d$.

Bolt tightening torque:

Threaded bolt M16	279 Nm (206 lb.ft)
Threaded bolt 5/8" - 11 UNC.	260 Nm (192 lb.ft)

MOUNTING AND MAINTENANCE OF WORM DRIVES

Mounting is based upon gradual tightening of the bolts, while alternating opposite one another. First, gently tighten all bolts with half the prescribed moment, then second proceed with full prescribed tightening moment.

When completed final inspection of the prescribed tightening moment should be performed.

After mounting, it is necessary to:

- check the lubrication of all worm drive functional parts (especially of the gear).
- measure the initial tilting clearance under minimum and maximum loads.
- record measured data in the machine operation diary.

The maintenance is based upon the regular relubrication of the slewing ring raceways, gear and worm bearings. Inspection of wear should be completed as well.

Open/Uncovered Worm Drives:

In a presumed constant cyclical operation (application such as an assembling platform) it is sufficient for functional parts to be lubricated once per year.

The recommended lubricants are:

- lithium lubricants of the consistency 2 with EP additives for the raceways of the slewing ring and worm bearings.
- grease for open drives for the gear.

The relubrication of the slewing ring raceway, worm bearing and gear must be performed so that all functional surfaces are lubricated to approximately 70 per cent (the filling factor 70 %).

When more frequent use of the equipment is applicable (more than 8 hours/day) or at a small swing angle it is suitable to relubricate more often, i. e. approximately once every 4 months.

Covered Worm Drives:

- they are filled with fully synthetic grease with a long life period “Klübersynth GE 14-151” or its equivalent.
- they require the relubrication of the slewing ring raceway and gear. The relubrication interval depends on operation frequency. The worm bearings relubrication is not needed, for the initial lubrication lasts the entire period of the presumed life (6 000 operating hours).

The Inspection of Wear

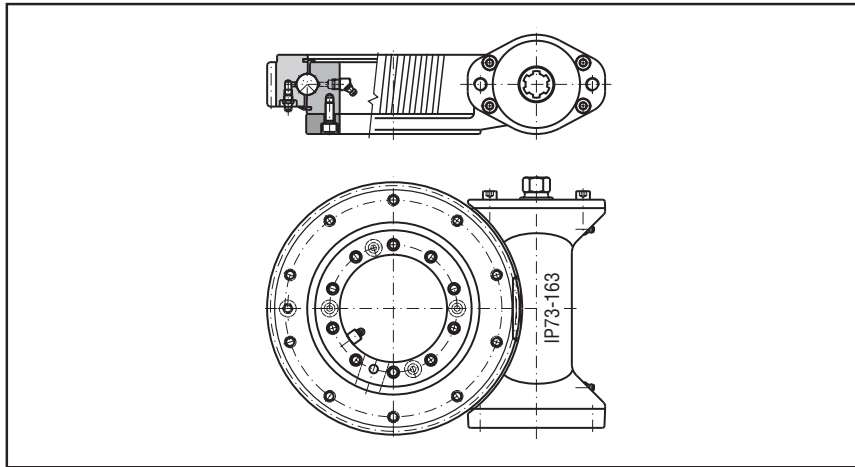
The indicator of the wear of the slewing ring raceway is an increase in the tilting clearance.

The permissible increase in the tilting clearance may be max. app. 1.5 mm. The signal of the gear wear is an increased backlash. The permissible magnitude of the backlash depends on the swing drive type applied.

Note:

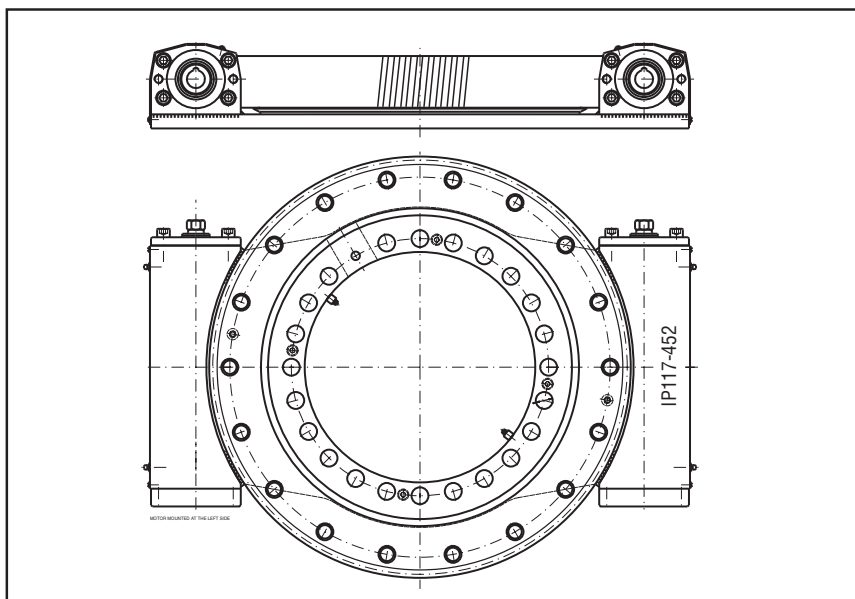
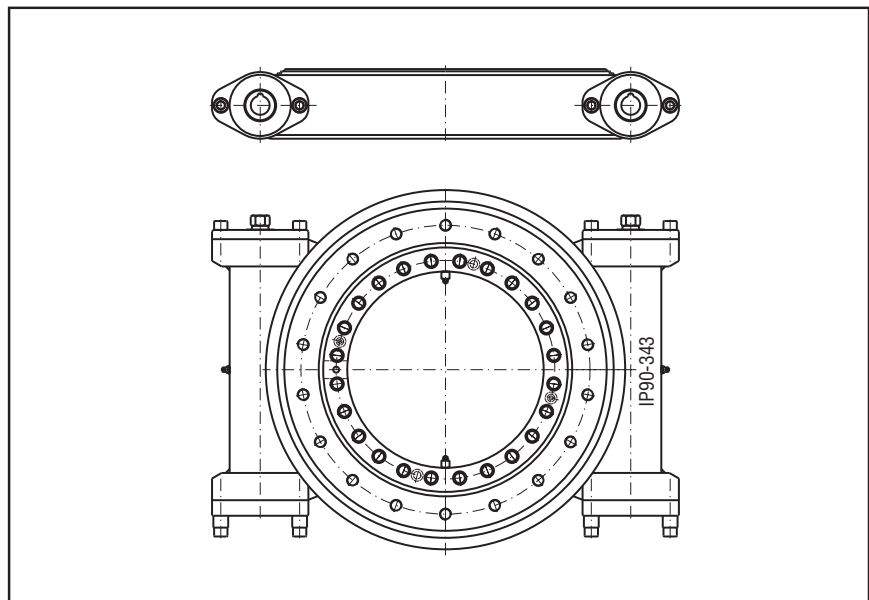
In the event of an excessive wear or an increase in the slewing ring tilting clearance or backlash of the gear engaged, it is necessary to consult the PSL, a. s., Technical Department for permissible values.

OTHER PSL WORM DRIVE DESIGNS



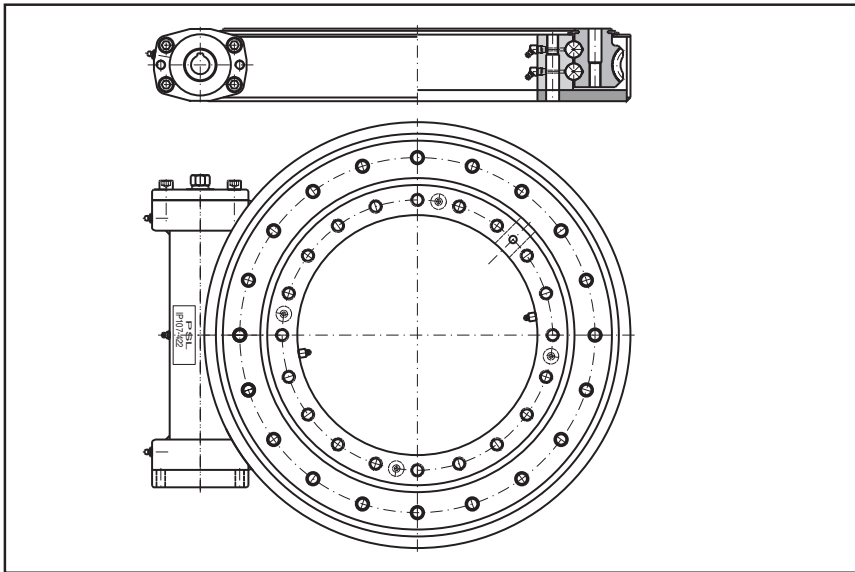
Mini worm drive
IP73-163L/R
Design A

**Medium worm drive
with 2 worms**
IP90-343D
Design D



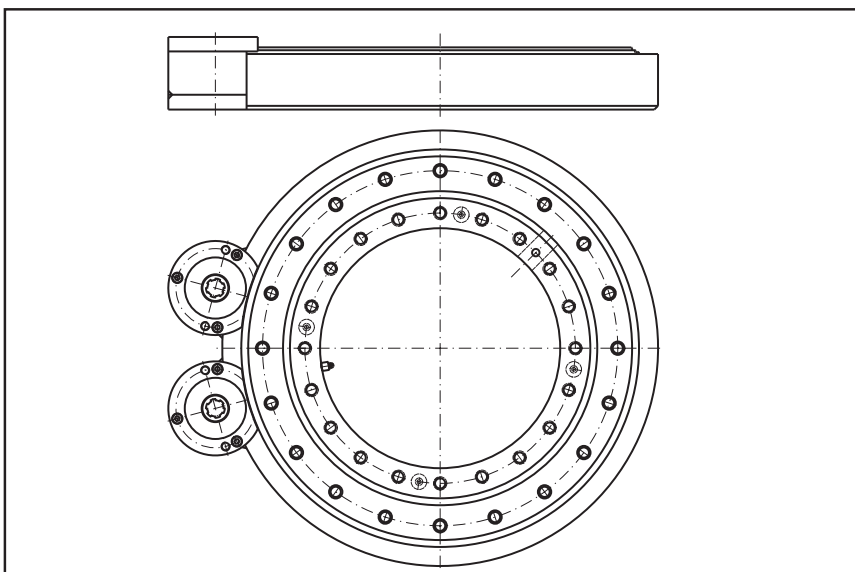
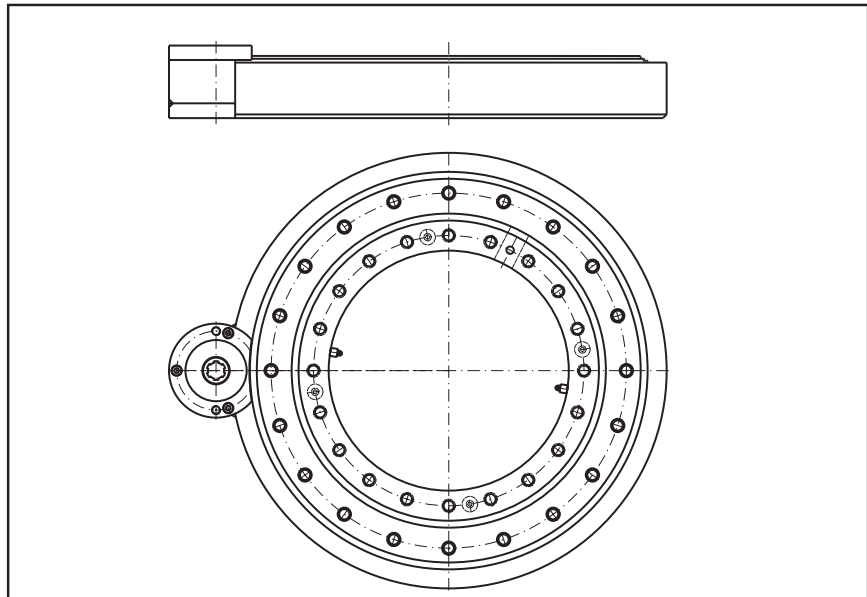
**Heavy duty worm drive
with 2 worms**
IP117-452D
Design B

OTHER PSL WORM DRIVE DESIGNS



**Heavy duty worm drive
with double row
slewing ring**
IP107-422L/R
Design H

**Heavy duty drive
with pinion**
IP8,6-422
Design R



**Heavy duty drive
with 2 pinions**
IP8,6-422D
Design R

WORM DRIVE – DESIGN WORKSHEET

Company:
Address:

Name:
Department
Tel:
Fax:
E-mail:

Application/Type of machine:

Axis of rotation*:

- vertical ☐
- horizontal ☐
- angular ☐ °
- variable ☐

Rotation mode*:

- continuous rotation ☐
- intermittent rotation ☐
- cyclic or positioning only ☐

Load characteristics*

Bearing under

compression

☐

tension

☐

shocks

☐

vibrations

☐

Load

working load

average

maximum

test

extreme

axial

[kN]

lb

radial

[kN]

lb

tilting moment

[kNm]

[10³.lb.ft]

torque

[kNm]

[10³.lb.ft]

Drive ratio*

60

☐

85

☐

103

☐

65

☐

90

☐

107

☐

other

Rotational speed

average..... min⁻¹

maximum min⁻¹

cyclic operation: number of cycles/hour
working angle

..... cycles/hour
±

Operating conditions

number of operating hours hours/day

thereof rotational (oscillatory) time %

number of operating hours hours/year

required life hours

Operating temperature

..... °C

outer ring

..... °C

inner ring

..... °C

Driving motor

type

torque

coupling of driving motor* at the left side ☐

at the right side ☐

Remarks: (environmental conditions, dustiness, humidity, aggressive properties, etc.)

Necessary data

Required date of offer

Quoted quantity pcs

Required date of delivery

Annual requirements pcs/year

Please fully complete this form. Incomplete information will delay our proposal.

Individual consultation required. Please call for appointment.* ☐

*Please check appropriate

Date:

Signature:



NOTES

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